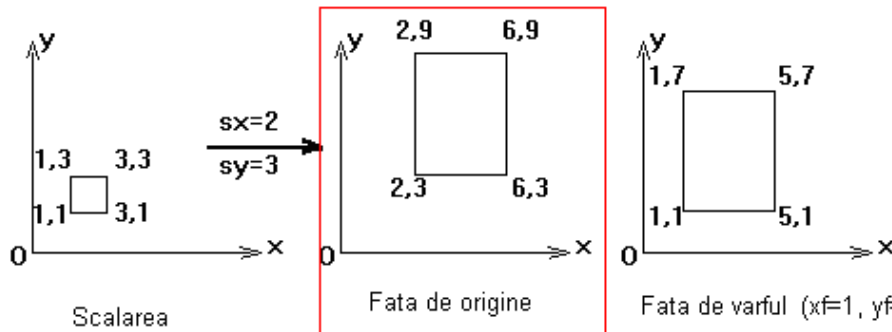
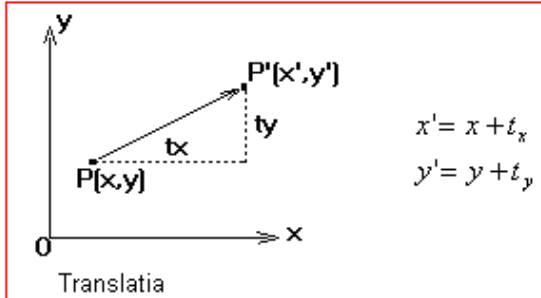
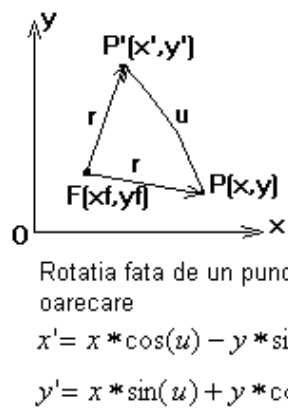
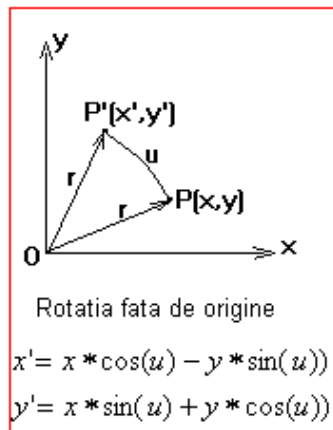
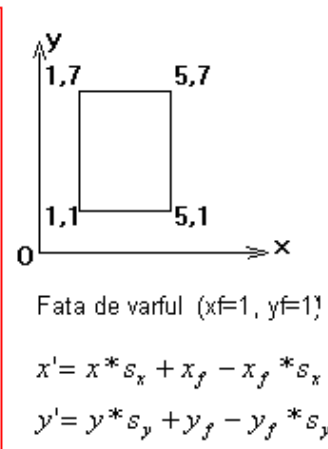
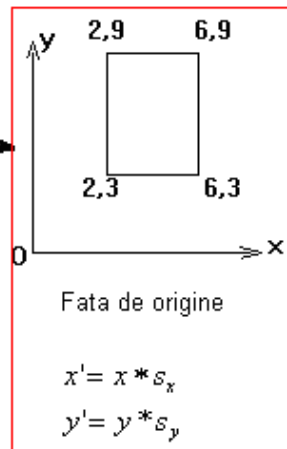


TRANSFORMARI GEOMETRICE 2D (BIDIMENSIONALE)

1. TRANSFORMARILE ELEMENTARE

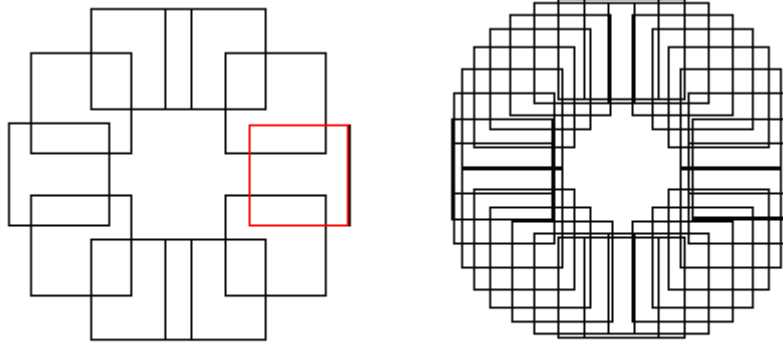


$$[x' y'] = [x y] \begin{bmatrix} s_x & 0 \\ 0 & s_y \end{bmatrix}$$

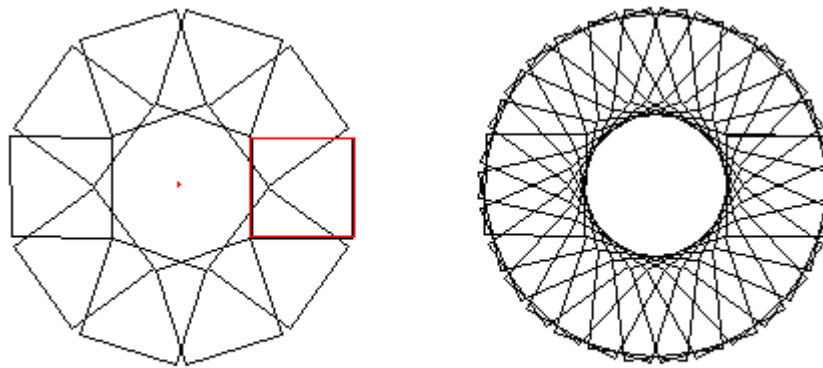


$$[x' y'] = [x y] \begin{bmatrix} \cos(u) & \sin(u) \\ -\sin(u) & \cos(u) \end{bmatrix}$$

Rotatia fata de origine



Translatia patratului pe circumferinta unui cerc



Rotatia patratului in jurul unui punct

2. COMPUNEREA TRANSFORMARILOR ELEMENTARE

- Inmultirea matricilor corespunzatoare transformarilor
- Coordonate omogene:

$$P(x,y) \rightarrow [xw, yw, w] \text{ sau}$$

$$\begin{bmatrix} xw \\ yw \\ w \end{bmatrix}$$

$xw = x * w$; $yw = y * w$; w – orice număr real

Ex: $P(2, 0.5) \rightarrow [2, 0.5, 1], [4, 1, 2], [20, 5, 10]$

Exprimarea transformărilor elementare în coordonate omogene

Translația

$$[x' \ y' \ 1] = [x \ y \ 1] \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ t_x & t_y & 1 \end{bmatrix} \text{ sau } \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

Scalarea față de origine

$$[x' \ y' \ 1] = [x \ y \ 1] \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ sau } \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

rotația față de origine

$$[x' \ y' \ 1] = [x \ y \ 1] \begin{bmatrix} \cos(u) & \sin(u) & 0 \\ -\sin(u) & \cos(u) & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ sau } \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos(u) & -\sin(u) & 0 \\ \sin(u) & \cos(u) & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

Expresiile matematice ale scalării și rotației față de un punct oarecare din plan se pot obține prin compunerea următoarelor transformări:

1. Translația prin care punctul fix al transformării ajunge în origine;
2. Scalarea / rotația față de origine;
3. Translația inversă celei de la punctul 1.

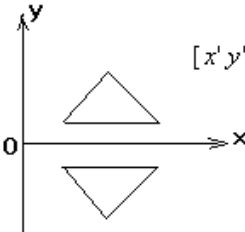
Scalarea față de punctul F (x_f, y_f)

$$[x' \ y' \ 1] = [x \ y \ 1] \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -x_f & -y_f & 1 \end{bmatrix} \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ x_f & y_f & 1 \end{bmatrix} \text{ sau}$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & x_f \\ 0 & 1 & y_f \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -x_f \\ 0 & 1 & -y_f \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

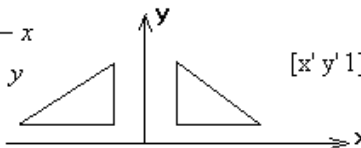
3. ALTE TRANSFORMARI 2D

OGLINDIREA



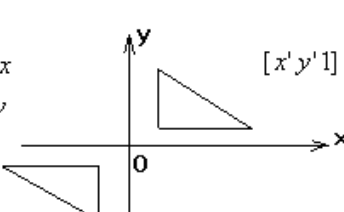
$x' = x$
 $y' = -y$

$$[x' \ y' \ 1] = [x \ y \ 1] \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ sau } \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$



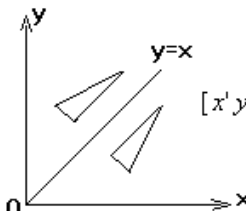
$x' = -x$
 $y' = y$

$$[x' \ y' \ 1] = [x \ y \ 1] \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ sau } \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$



$x' = -x$
 $y' = -y$

$$[x' \ y' \ 1] = [x \ y \ 1] \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ sau } \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$



$x' = y$
 $y' = x$

$$[x' \ y' \ 1] = [x \ y \ 1] \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ sau } \begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

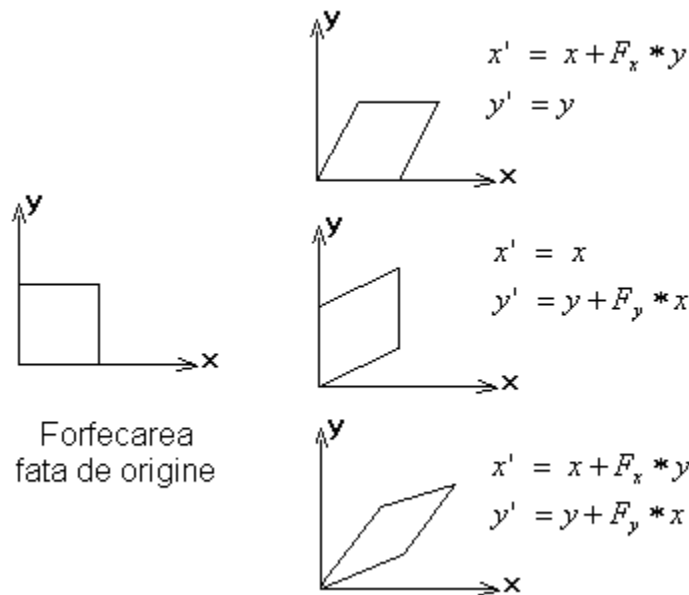
Oglindirea față de o dreaptă oarecare: transformare compusa

1. O translație, astfel încât dreapta să treacă prin origine;
2. O rotație față de origine astfel încât dreapta să se suprapună peste una dintre axele principale;
3. Oglindirea față de axa principală peste care a fost suprapusă dreapta.
4. Rotația inversă celei de la punctul 2;
5. Translația inversă celei de la punctul 1.

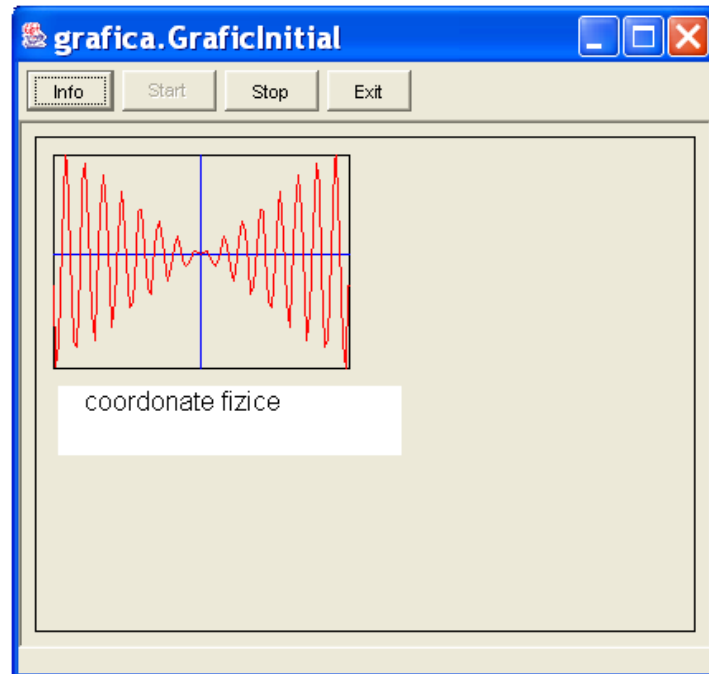
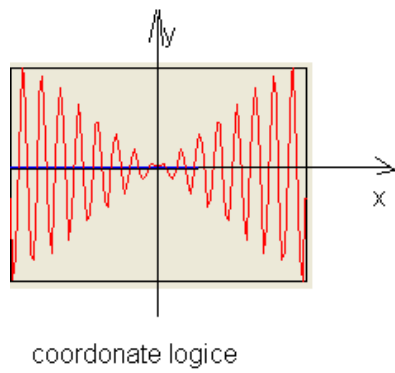
În notație matricială, secvența de mai sus se exprimă astfel:

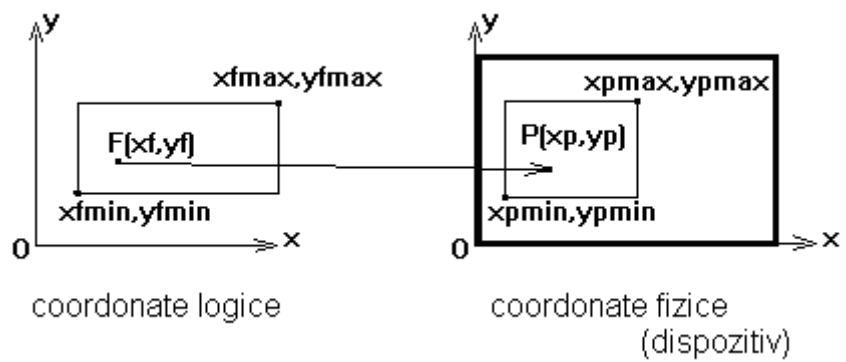
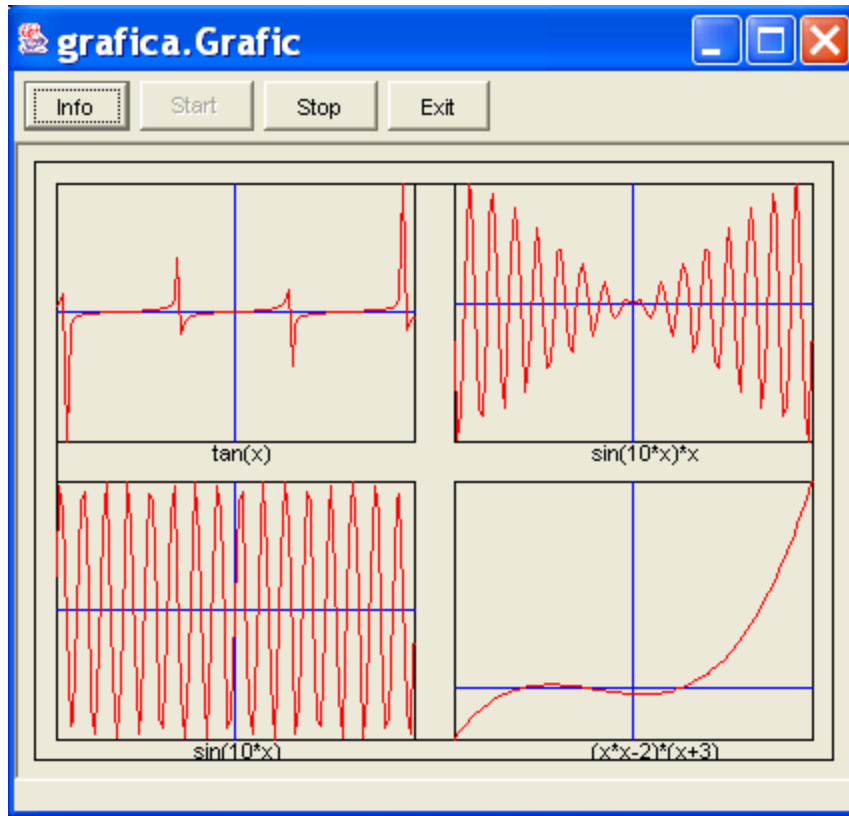
$$M = T * R * O * R^{-1} * T^{-1} \text{ sau } M = T^{-1} * R^{-1} * O * R * T$$

FORFECAREA



TRANSFORMAREA DE VIZUALIZARE 2D





$$\frac{xp - xp \min}{xp \max - xp \min} = \frac{xf - xf \min}{xf \max - xf \min}$$

$$\frac{yp - yp \min}{yp \max - yp \min} = \frac{yf - yf \min}{yf \max - yf \min}$$

$$sx = \frac{xp \text{ max} - xp \text{ min}}{xf \text{ max} - xf \text{ min}}$$

$$sy = \frac{yp \text{ max} - yp \text{ min}}{yf \text{ max} - yf \text{ min}}$$

$$\text{\cyrillic{S}i } tx = xpmin - sx * xfmin \quad ty = ypmin - sy * yfmin$$

$$xp = xf * sx + tx$$

$$yp = yf * sy + ty$$