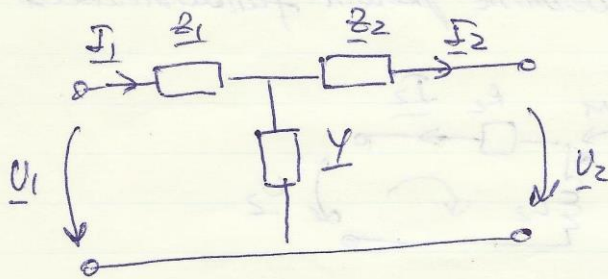


11.2. Schemele echivalente ale cuadipolului liniar

Cele mai utilizate sunt schemele în T și π .

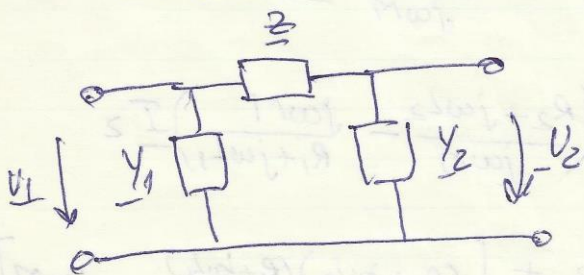


$$\begin{aligned} \underline{U}_1 &= \underline{z}_1 (\underline{I}_2 + \underline{Y} (\underline{z}_2 \underline{I}_2 + \underline{U}_2)) + \underline{z}_2 \underline{I}_2 + \underline{U}_2 \\ &= \underline{z}_1 \underline{I}_2 + \underline{z}_1 \underline{z}_2 \underline{Y} \underline{I}_2 + \underline{z}_1 \underline{Y} \underline{U}_2 + \underline{z}_2 \underline{I}_2 + \underline{U}_2 \end{aligned}$$

$$\underline{U}_1 = \underbrace{(1 + \underline{z}_1 \underline{Y})}_{\underline{A}} \underline{U}_2 + \underbrace{(\underline{z}_1 + \underline{z}_2 + \underline{z}_1 \underline{z}_2 \underline{Y})}_{\underline{B}} \underline{I}_2$$

$$\begin{aligned} \underline{I}_1 &= \underline{I}_2 + \underline{Y} (\underline{z}_2 \underline{I}_2 + \underline{U}_2) = \\ &= \underbrace{\underline{Y} \underline{U}_2}_{\underline{C}} + \underbrace{(1 + \underline{z}_2 \underline{Y})}_{\underline{D}} \underline{I}_2 \end{aligned}$$

Schema echiv. în π



$$\begin{aligned} \underline{A} &= 1 + \underline{z} \underline{Y}_2 \\ \underline{B} &= \underline{z} \\ \underline{C} &= \underline{Y}_1 + \underline{Y}_2 + \underline{Y}_1 \underline{z} \underline{Y}_2 \\ \underline{D} &= 1 + \underline{z} \underline{Y}_1 \end{aligned}$$

Ca urmare se pot deduce parametrii cuadipolului echivalent în T sau în π

Datorită relațiilor de echivalență între sistemele de ecuații se pot deduce relații între parametrii cuadripolului Astfel, pt ec. în admitanțe avem:

$$\begin{cases} \underline{I}_1 = \underline{Y}_{11} \underline{U}_1 + \underline{Y}_{12} \underline{U}_2 \\ \underline{I}_2 = \underline{Y}_{21} \underline{U}_1 + \underline{Y}_{22} \underline{U}_2 \end{cases} \quad \begin{cases} | : \underline{Y}_{11} \\ | : \underline{Y}_{21} \end{cases}$$

$$\frac{\underline{I}_1}{\underline{Y}_{11}} = \underline{U}_1 + \frac{\underline{Y}_{12}}{\underline{Y}_{11}} \underline{U}_2$$

$$\frac{\underline{I}_2}{\underline{Y}_{21}} = \underline{U}_1 + \frac{\underline{Y}_{22}}{\underline{Y}_{21}} \underline{U}_2$$

$$\frac{\underline{I}_1}{\underline{Y}_{11}} - \frac{\underline{I}_2}{\underline{Y}_{21}} = \left(\frac{\underline{Y}_{12}}{\underline{Y}_{11}} - \frac{\underline{Y}_{22}}{\underline{Y}_{21}} \right) \underline{U}_2$$

$$\underline{I}_1 = \frac{\underline{Y}_{21} \underline{Y}_{12} - \underline{Y}_{11} \underline{Y}_{22}}{\underline{Y}_{21}} \underline{U}_2 + \frac{\underline{Y}_{11}}{\underline{Y}_{21}} \underline{I}_2$$

$$\Rightarrow \underline{C} = \frac{\underline{Y}_{21} \underline{Y}_{12} - \underline{Y}_{11} \underline{Y}_{22}}{\underline{Y}_{21}} \quad \underline{D} = \frac{\underline{Y}_{11}}{\underline{Y}_{21}} \quad (7)$$

Din a 5-a ec:

$$\underline{Y}_{21} \underline{U}_1 = \underline{I}_2 - \underline{Y}_{22} \underline{U}_2$$

$$\underline{U}_1 = -\frac{\underline{Y}_{22}}{\underline{Y}_{21}} \underline{U}_2 + \frac{1}{\underline{Y}_{21}} \underline{I}_2$$

$$\Rightarrow \left. \begin{cases} \underline{A} = -\frac{\underline{Y}_{22}}{\underline{Y}_{21}} \\ \underline{B} = \frac{1}{\underline{Y}_{21}} \end{cases} \right\} (8)$$

